

Statistical Inference of biological networks

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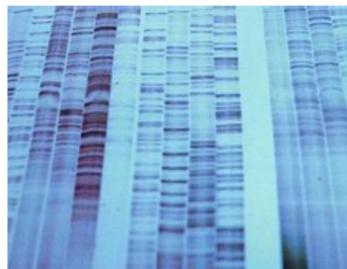
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Toulouse, juin 2008.



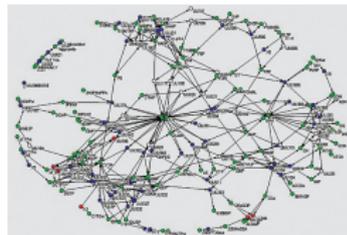
From genomics to postgenomics

Genomics: genome sequencing of various organisms (human genome ~ 04)



Postgenomics: try to understand how it works!

- Massive "omics" data sets
- Involves biology, physics, computer sciences, maths...



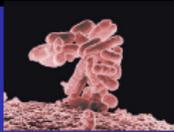
Size of genomes

Genome of a bacteria:

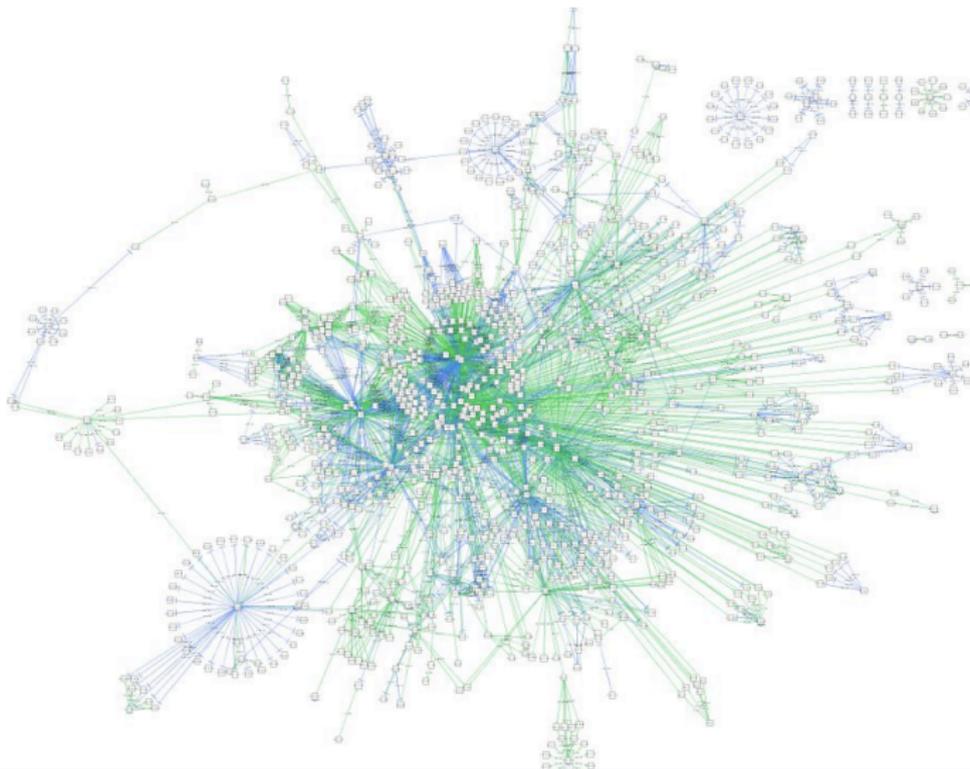
- 1 to 5 millions of base pairs
- 1 to 5 thousands genes
- a few millions of possible gene-gene interactions

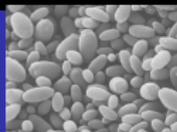
Human genome:

- around 3.4 billions of base pairs
- around 25 000 genes
- more than 100 millions of possible gene-gene interactions



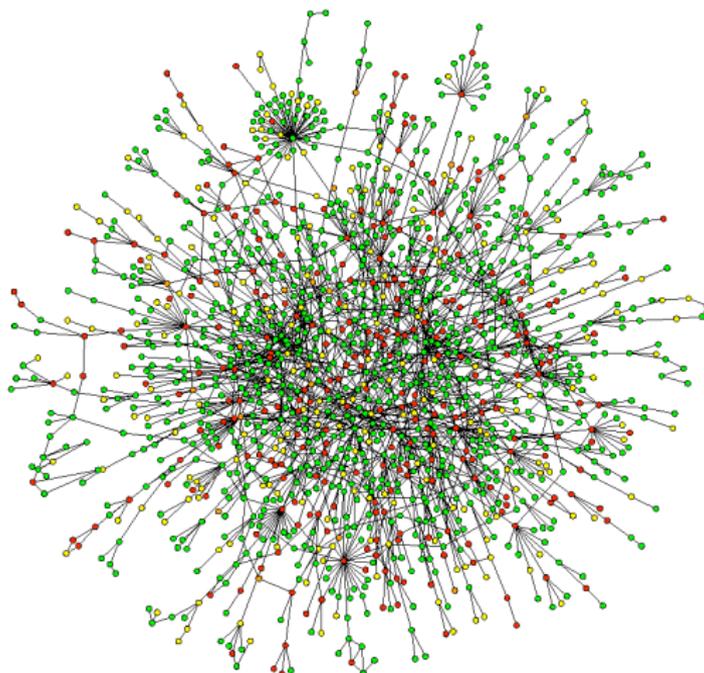
Gene - gene regulation network of *E. coli*

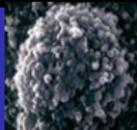




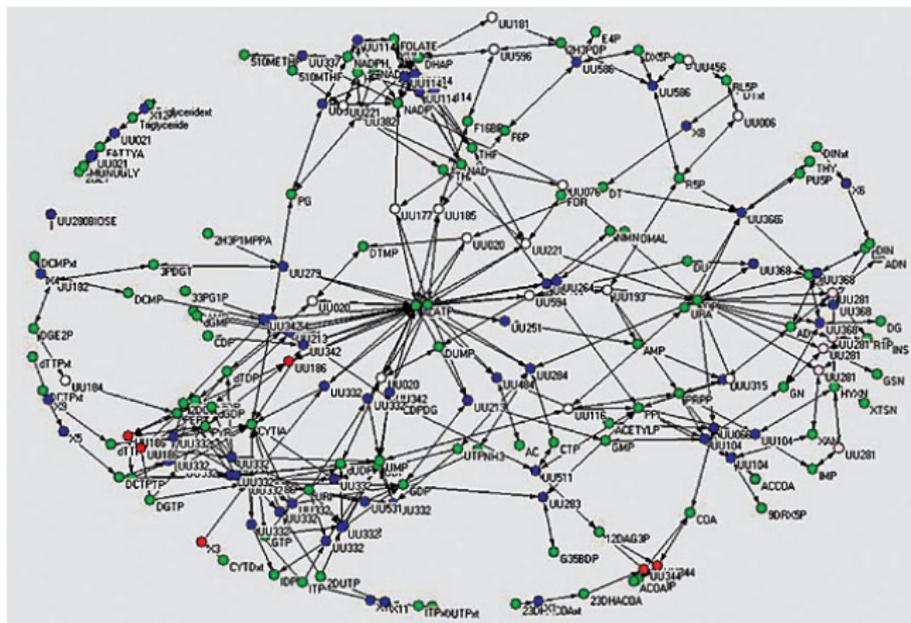
Protein - protein network of *S. cerevisiae*

1458 proteins (vertices) and their 1948 known interactions (edges)





Metabolic pathway of *U. urealyticum*



Why focusing on regulation networks?

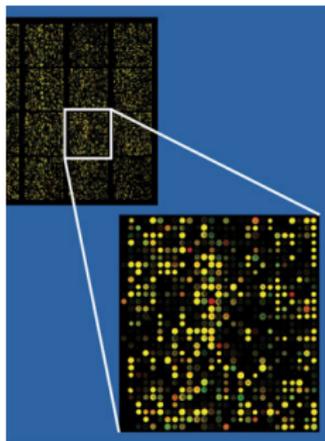
- **Traditional biology** studies the specific functions of individual genes, proteins or cells.

- **System biology** tries to understand how the whole system works by investigating the interaction network between genes, proteins, metabolites, etc.

→ emergent properties

Inferring gene regulation networks

Data: massive transcriptomic data sets produced by microarrays.



- **Differential analysis** of data obtained in different conditions: with or without deletion of a gene, with or without stress, etc.
- **Analysis of the conditional dependences** in the data (exploits the whole data set).

A few statistical tools

Descriptive tools:

- Kernel methods (supervised learning)

Model based tools:

- Bayesian Networks
- Gaussian Graphical Models

Gaussian Graphical Models

Gaussian Graphical Models

Statistical model: The transcription levels $(X^{(1)}, \dots, X^{(p)})$ of the p genes are modeled by a Gaussian law in \mathbb{R}^p .

Graph of the conditional dependences: graph \mathbf{g} with

an edge $i \overset{\mathbf{g}}{\sim} j$ between the genes i and j
iff
 $X^{(i)}$ and $X^{(j)}$ are not independent given $\{X^{(k)}, k \neq i, j\}$

regulation network \longleftrightarrow graph \mathbf{g}

The task of the statistician

Goal: estimate \mathbf{g} from a sample X_1, \dots, X_n .

Main difficulty: $n \ll p$

- $p \approx$ a few 100 to a few 1000 genes
- $n \approx$ a few tens

Some new algorithms

New algorithms: based on thresholding or regularization

Multiple testing	Convex minimization
<ul style="list-style-type: none">- Drton & Perlman (2004)- Schäfer & Strimmer (2005)- Wille & Bühlmann (2006)- Verzelen & Villers (2007)- Bühlmann & Kalisch (2008)...	<ul style="list-style-type: none">- Meinshausen & Bühlmann (2006)- Huang <i>et al.</i> (2006)- Yuan & Lin (2007)- Banerjee <i>et al.</i> (2007)- Friedman <i>et al.</i> (2007)...

- quite disappointing numerical performances (Villers *et al.* 2008)
- no theoretical results or in an asymptotic framework (with strong hypotheses on the covariance)

Penalized empirical risk estimation

Partial correlations

Hypothesis: $(X^{(1)}, \dots, X^{(p)}) \sim \mathcal{N}(0, C)$ in \mathbb{R}^p , with C positive definite.

Notation: We write $\theta = \left(\theta_k^{(j)}\right)$ for the $p \times p$ matrix such that $\theta_j^{(j)} = 0$ and $\mathbb{E}(X^{(j)} | X^{(k)}, k \neq j) = \sum_{k \neq j} \theta_k^{(j)} X^{(k)}$.

Skeleton of θ : we have $\theta_i^{(j)} = \frac{\text{Cov}(X^{(i)}, X^{(j)} | X^{(k)}, k \neq i, j)}{\text{Var}(X^{(i)} | X^{(k)}, k \neq j)}$ so

$$\theta_i^{(j)} \neq 0 \iff i \overset{g}{\sim} j$$

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Estimation strategy

Goal: Estimate θ from a sample X_1, \dots, X_n with quality criterion

$$\text{MSEP}(\hat{\theta}) = \mathbb{E} \left[\|C^{1/2}(\hat{\theta} - \theta)\|_{\rho \times \rho}^2 \right] = \mathbb{E} \left[\|X_{new}^T(\hat{\theta} - \theta)\|_{1 \times p}^2 \right]$$

Estimation strategy:

- 1 Choose a collection \mathcal{G} of candidate graphs.
- 2 Associate to each graph $g \in \mathcal{G}$ an estimator $\hat{\theta}_g$ of θ .
- 3 Select one of them by minimizing a penalized empirical risk.

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1- Collection of candidate graphs

Choice of a collection \mathcal{G} of candidate graphs

Examples

- Set of all the graphs with p vertices and degree $\leq D$,
- Set of all the graph with p vertices and degree $\leq D$ containing a known subgraph g_o .

Model associated to $g \in \mathcal{G}$ to estimate θ :

$$g \curvearrowright \Theta_g = \left\{ \theta \in \mathbb{R}^{p \times p} : i \not\sim_j \Rightarrow \theta_i^{(j)} = 0 \right\}$$

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2- Estimator $\hat{\theta}_g$ associated to g

Characterization: $\theta = \operatorname{argmin}_{A \in \Theta} \|C^{1/2}(I - A)\|_{p \times p}^2$

where $\Theta =$ set of matrices with null diagonal.

Empirical version: $C^{1/2} \leftrightarrow X = \begin{bmatrix} X_1^T \\ \vdots \\ X_n^T \end{bmatrix} = [X^{(1)}, \dots, X^{(p)}]$

Estimator associated to g :

$$\hat{\theta}_g = \operatorname{argmin}_{A \in \Theta_g} \|X(I - A)\|_{n \times p}^2$$

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3- Which estimator should be chosen among $\{\hat{\theta}_g, g \in \mathcal{G}\}$?

Ideal: choose $\hat{\theta}_{g^*}$ minimizing

$$\text{MSEP}(\hat{\theta}_g) = \mathbb{E} \left(\|C^{1/2}(\theta - \hat{\theta}_g)\|^2 \right) \approx \|C^{1/2}(\theta - \theta_g)\|^2 + \sum_{j=1}^p \frac{\text{deg}(j)}{nC_{jj}^{-1}}$$

Selection criterion: set $\hat{\theta} = \hat{\theta}_{\hat{g}}$ where \hat{g} minimizes over \mathcal{G}

$$\text{crit}(g) = \underbrace{\|X(I - \hat{\theta}_g)\|^2}_{\text{empirical MSEP}}$$

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which penalty pen?

The penalty

Notation: let $\text{EDkhi}(d, N, x)$ be the inverse of

$$x \mapsto \mathbb{P} \left(F_{d+2, N} \geq \frac{x}{d+2} \right) - \frac{x}{d} \mathbb{P} \left(F_{d, N+2} \geq \frac{N+2}{Nd} x \right)$$

where $F_{d, N}$ is a Fisher(d, N).

Penalty: For $K > 1$ we set

$$\begin{aligned} \text{pen}(d) &= K \frac{n-d}{n-d-1} \text{EDkhi} \left[d+1, n-d-1, (C_{p-1}^d (d+1)^2)^{-1} \right] \\ &\lesssim K \left(1 + e^\rho \sqrt{2 \log p} \right)^2 (d+1) \quad \text{when } d \leq \rho \frac{n}{2 \log p}. \end{aligned}$$

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Theorem: risk bound.

When $\deg(\mathcal{G}) = \max \{ \deg(g), g \in \mathcal{G} \}$ fulfills

$$\deg(\mathcal{G}) \leq \rho \frac{n}{2(1.1 + \sqrt{\log p})^2}, \quad \text{for some } \rho < 1,$$

then the MSEP of $\hat{\theta}$ is bounded by

$$\text{MSEP}(\hat{\theta}) \leq c_{K,\rho} \log(p) \inf_{g \in \mathcal{G}} \left\{ \text{MSEP}(\hat{\theta}_g) \vee \frac{\|C^{1/2}(I - \theta)\|^2}{n} \right\} + R_n$$

where $R_n = O(\text{Tr}(C)e^{-\kappa_\rho n})$.

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Optimality?

- 1 Where does the condition on the degree come from?
- 2 Can we choose a smaller penalty?

Theory

Condition on the degree

Which size of graph can we hope to estimate?

Prediction error:

$$\text{MSEP}(\hat{\theta}) = \mathbb{E}(\|C^{1/2}(\theta - \hat{\theta})\|^2) = \mathbb{E}(\|C^{1/2}(I - \hat{\theta})\|^2) - \|C^{1/2}(I - \theta)\|^2$$

To control the MSEP, we would like to have with large probability

$$(1 - \delta) \|C^{1/2}(I - \hat{\theta})\|_{p \times p} \leq \frac{1}{\sqrt{n}} \|X(I - \hat{\theta})\|_{n \times p} \leq (1 + \delta) \|C^{1/2}(I - \hat{\theta})\|_{p \times p}$$

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Proposition: From empirical to population MSEP

When $\deg(\mathcal{G}) = \max \{\deg(g), g \in \mathcal{G}\}$ fulfills

$$\deg(\mathcal{G}) \leq \rho \frac{n}{2(1.1 + \sqrt{\log \rho})^2}, \quad \text{for some } \rho < 1,$$

then for $\delta > \sqrt{\rho}$,

we have with probability $\geq 1 - 2 \exp(-n(\delta - \sqrt{\rho})^2/2)$

$$(1 - \delta) \|C^{1/2}(I - A)\| \leq \frac{1}{\sqrt{n}} \|X(I - A)\| \leq (1 + \delta) \|C^{1/2}(I - A)\|$$

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for all matrices $A \in \bigcup_{g \in \mathcal{G}} \Theta_g$.

Lemma: Restricted Infimum of Random Matrices

Consider a $n \times p$ matrix Z with $n \leq p$ and i.i.d. $Z_{i,j} \sim \mathcal{N}(0, 1)$. Consider also a collection V_1, \dots, V_N of subspaces of \mathbb{R}^p with dimension $d < n$.

Then for any $x > 0$

$$\mathbb{P} \left[\inf_{v \in V_1 \cup \dots \cup V_N} \frac{\frac{1}{\sqrt{n}} \|Zv\|}{\|v\|} \leq 1 - \frac{\sqrt{d} + \sqrt{2 \log N} + \delta_N + x}{\sqrt{n}} \right] \leq e^{-x^2/2}$$

where $\delta_N = \frac{1}{N\sqrt{8 \log N}}$.

Lemma: Restricted Supremum of Random Matrices

Consider a $n \times p$ matrix Z with $n \leq p$ and i.i.d. $Z_{i,j} \sim \mathcal{N}(0, 1)$. Consider also a collection V_1, \dots, V_N of subspaces of \mathbb{R}^p with dimension $d < n$.

Then for any $x > 0$

$$\mathbb{P} \left[\sup_{v \in V_1 \cup \dots \cup V_N} \frac{\frac{1}{\sqrt{n}} \|Zv\|}{\|v\|} \leq 1 + \frac{\sqrt{d} + \sqrt{2 \log N} + \delta_N + x}{\sqrt{n}} \right] \leq e^{-x^2/2}$$

where $\delta_N = \frac{1}{N\sqrt{8 \log N}}$.

A geometrical constraint

When $C = I$, there exists some constant $c(\delta) > 0$ such that for any n, p, \mathcal{G} fulfilling

$$\text{deg}(\mathcal{G}) \geq c(\delta) \frac{n}{1 + \log(p/n)},$$

there exists no $n \times p$ matrix X fulfilling

$$(1 - \delta) \|C^{1/2}(I - A)\| \leq \frac{1}{\sqrt{n}} \|X(I - A)\| \leq (1 + \delta) \|C^{1/2}(I - A)\|$$

for all matrices $A \in \bigcup_{g \in \mathcal{G}} \Theta_g$.

Theory

Minimal penalty

Minimal size of $\text{pen}(d)$?

In the simple case where $\mathbf{g} = \emptyset$ we would like to select a "small" $\hat{\mathbf{g}}$

Minimal penalty

$$\implies \text{"pen}(d) \geq 2d \log(p) \text{"}$$

Proposition: Over-fitting

For some $D < n < p$ and $p \geq e^{2/(1-\gamma)} + 1$, assume that:

- $\text{pen}(d) = 2(1 - \gamma)d \log(p - 1)$ with $\gamma \in (0, 1)$,
- $\{\text{graphs with at most } D \text{ edges}\} \subset \mathcal{G}$,
- $\mathbf{g} = \emptyset$.

Then,

$$\mathbb{P} \left(\text{deg}(\hat{g}) \geq \frac{c(\gamma) \min(n, p^{\gamma/4})}{(\log p)^{3/2}} \wedge \lfloor \gamma D / 8 \rfloor \right) \geq 1 - \frac{3}{p-1} - 2e^{-\gamma^2 n / 8^3}$$

where $c(\gamma) > 0$ is an (explicit) constant depending on γ only.

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In practice

Numerical performance

Numerical performance

Comparison to Meinshausen & Buhlmann's procedure.

Setting:

- random "Erdos-Reny" graphs & random covariance matrices
- $n = 15$ observations

Focus on two settings:

- when the density of the graph increases
- when the number p of covariables increases

$n = 15$, $p = 10$, edges = 10%, 30% & 33%

edges = 10%

	KGGM	MB
risk/oracle	2.5	3.3
Puissance	81%	81%
FDR	4.4%	3.7%

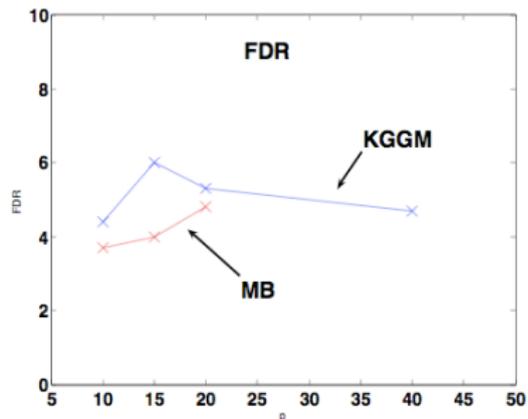
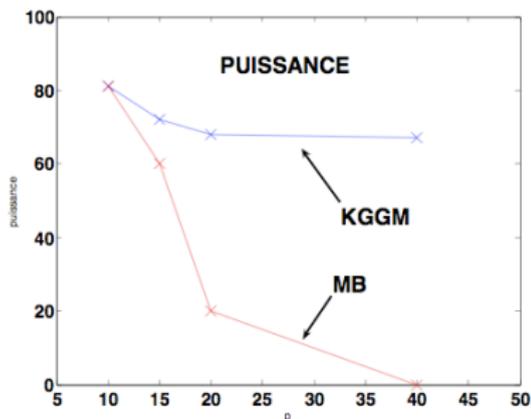
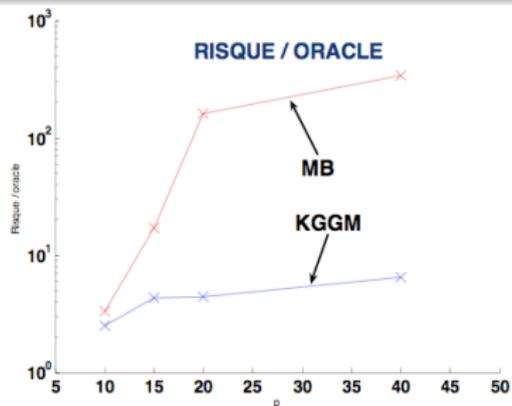
edges = 30%

	KGGM	MB
risk/oracle	4.9	6.9
Puissance	20%	14%
FDR	5.4%	2.9%

edges = 33%

	KGGM	MB
risk/oracle	4.9	6.4
Puissance	10%	3.5%
FDR	4.1%	1.1%

When p increases ($n = 15$, fixed sparsity)



Conclusion

Some nice features:

- **good theoretical properties:** non-asymptotic control of the MSEP with no condition on the covariance matrix C
- **good numerical performances:** even when $n \ll p$

BUT

- **very high numerical complexity:**
typically $n \times p^{\deg(\mathcal{G})+1}$

\implies cannot be used in practice when $p > 50 \dots$

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Some nice features:

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\implies cannot be used in practice when $p > 50 \dots$

Practical implementation

Ongoing work: with S. Huet and N. Verzelen

Reduction of the collection of graphs, with the aim to find a balance between

- computational efficiency
- estimation accuracy

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